

SEARCH AND RESCUE ROBOTICS

1. INTRODUCTION

- 1.1. Presentation.
- 1.2. Beginnings.
- 1.3. Rescue Robots.

2. TYPES OF RESCUE ROBOTS

2.1. SIZE

- 2.1.1. Man-packable.
- 2.1.2. Man-portable.
- 2.1.3. Maxi-sized.

2.2. TYPES

- 2.2.1. UGVs.
 - 2.2.1.1. Description.
 - 2.2.1.2. Small UGVs.
 - 2.2.1.3. Large UGVs.
 - 2.2.1.4. Uses and examples.
- 2.2.2. UAVs.
 - 2.2.2.1. Description.
 - 2.2.2.2. Fixed-wing.
 - 2.2.2.3. Rotary-wing.
 - 2.2.2.4. Uses and examples.
- 2.2.3. USVs.
 - 2.2.3.1. Description.
 - 2.2.3.2. Uses.
- 2.2.4. UUVs.
 - 2.2.4.1. Description and uses.

3. EVALUATION

3.1. SIMULATIONS

- 3.1.1. Description.
- 3.1.2. Problems.
- 3.1.3. Examples of Software.
 - 3.1.3.1. RoboCup rescue simulation.
 - 3.1.3.2. USARSim.

3.2. PHYSICAL TESTBEDS

- 3.2.1. Description.

3.2.2. Problems.

3.2.3. RoboCup.

4. PROBLEMS

4.1. MOBILITY

4.2. COMMUNICATIONS

4.3. CONTROL

4.4. HUMAN-ROBOT INTERACTION

4.5. POWER

5. CONCLUSION

5.1. PROGRESS